

Gram-Schmidt Algorithm

Suppose $\mathcal{B} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is the basis for an subspace $S \subset \mathbb{R}^m$.

Form the set $\mathcal{B}^* = \{\vec{v}_1^*, \vec{v}_2^*, \dots, \vec{v}_n^*\}$ by

$$\vec{v}_1^* = \vec{v}_1$$

$$\vec{v}_2^* = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{v}_1^*}{\vec{v}_1^* \cdot \vec{v}_1^*} \vec{v}_1^*$$

$$\vec{v}_3^* = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{v}_2^*}{\vec{v}_2^* \cdot \vec{v}_2^*} \vec{v}_2^* - \frac{\vec{v}_3 \cdot \vec{v}_1^*}{\vec{v}_1^* \cdot \vec{v}_1^*} \vec{v}_1^*$$

$\vdots$

$$\vec{v}_i^* = \vec{v}_i - \sum_{j=1}^{i-1} \mu_{i,j} \vec{v}_j^* \quad \text{where } \mu_{i,j} = \frac{\vec{v}_i \cdot \vec{v}_j^*}{\vec{v}_j^* \cdot \vec{v}_j^*}, \quad 1 \leq j < i$$

Then $\mathcal{B}^*$ is an orthogonal basis for S .