PROBLEM SET #5

Due Friday, October 25, 2024 @ 12:30 pm Submit as single pdf file to Canvas

Remember to review the Guidelines for Problem Sets on the course webpage when writing up your solutions!

1. Let
$$A = \begin{bmatrix} -6 & 24 & 47 \\ 12 & 8 & -45 \\ -12 & -24 & 31 \end{bmatrix}$$

- (a) Give a basis for nul(A) and describe nul(A) geometrically.
- (b) Give a basis for col(A) and describe col(A) geometrically.

2. Let $T : \mathbb{R}^2 \to \mathbb{R}^2$ be the linear transformation defined by $T(\vec{\mathbf{x}}) = A\vec{\mathbf{x}}$ where $A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$.

- (a) Find a basis for $\ker(T)$ and describe $\ker(T)$ geometrically.
- (b) Find a basis for range(T) and describe range(T) geometrically.
- (c) Describe T in geometric terms.
 e.g. "T rotates the plane by π/3 radians counter-clockwise", or "T projects the plane onto the x-axis", etc. To be clear, T doesn't do either of these, but these are examples of how you can describe T. It may be useful to pick a few specific points in ℝ² and see what their image is under T.
- 3. (a) Let $S = {\vec{v_1}, \vec{v_2}, ..., \vec{v_k}}$ be a set of vectors in \mathbb{R}^n with k < n. Use a theorem from earlier in the semester to explain why S cannot be a basis for \mathbb{R}^n .
 - (b) Let $S = { \vec{v_1}, \vec{v_2}, ..., \vec{v_k} }$ be a set of vectors in \mathbb{R}^n with k > n. Use a theorem from earlier in the semester to explain why S cannot be a basis for \mathbb{R}^n .

(These problems are essentially the same as Exercises 4.3.29 and 4.3.30 from the text, Lay's Linear Algebra, 4th edition)

4. Let
$$A = \begin{bmatrix} 3 & 4 & 1 & -1 & 5 \\ 1 & 3 & -2 & 0 & 1 \\ -6 & -8 & -2 & 2 & -10 \\ 5 & 5 & 4 & -2 & 3 \end{bmatrix}$$

- (a) Find bases for col(A), nul(A), and row(A).
- (b) What is dim nul (A^T) ? Why?
- (c) One of your answers in (a) is also a basis for $col(A^T)$. Which one? Why?