(a) Give a basis for col(A) and a basis for nul(A).

(b) Describe col(A) and nul(A) geometrically.

2. Let 
$$\mathcal{H}$$
 be the subspace of  $\mathbb{R}^4$  spanned by  $\vec{\mathbf{v_1}} = \begin{bmatrix} 2\\4\\-2\\8 \end{bmatrix}$ ,  $\vec{\mathbf{v_2}} = \begin{bmatrix} 1\\5\\-4\\7 \end{bmatrix}$ , and  $\vec{\mathbf{v_3}} = \begin{bmatrix} 1\\2\\-1\\4 \end{bmatrix}$ .

Give a basis for  ${\mathcal H}$  and describe  ${\mathcal H}$  geometrically.

- 3. Let T : R<sup>2</sup> → R<sup>2</sup> be the linear transformation that rotates the plane by π/3 counter-clockwise and projects onto the *y*-axis.
  (a) Find a basis for ker(T) and describe ker(T) geometrically
  - (b) Find a basis for range(T) and describe range(T) geometrically

4. Let 
$$\vec{\mathbf{u_1}} = \begin{bmatrix} 1\\0\\4 \end{bmatrix}$$
,  $\vec{\mathbf{u_2}} = \begin{bmatrix} 2\\-1\\1 \end{bmatrix}$ ,  $\vec{\mathbf{u_3}} = \begin{bmatrix} -1\\2\\7 \end{bmatrix}$ , and  $\vec{\mathbf{b}} = \begin{bmatrix} 17\\-2\\4 \end{bmatrix}$ 

- (a) Show that the set  $\mathcal{B} = \{\vec{u_1}, \vec{u_2}, \vec{u_3}\}$  forms a basis for  $\mathbb{R}^3$ .
- (b) Write  $\vec{b}$  as a linear combination of the vectors in  $\mathcal B$

5. True or False: If 
$$\vec{\mathbf{v}_1} = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$$
,  $\vec{\mathbf{v}_2} = \begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix}$ ,  $\vec{\mathbf{v}_3} = \begin{bmatrix} 5 \\ 1 \\ 2 \end{bmatrix}$ , then  $\{\vec{\mathbf{v}_1}, \vec{\mathbf{v}_2}, \vec{\mathbf{v}_3}\}$  is a basis for  $\mathbb{R}^3$