PROBLEM SET #5

Due Thursday, October 28, 2021 @ midnight Submit as single pdf file to onCourse

Remember to review the Guidelines for Problem Sets on the course webpage.

1. Let
$$A = \begin{bmatrix} -6 & 24 & 47 \\ 12 & 8 & -45 \\ -12 & -24 & 31 \end{bmatrix}$$

- (a) Give a basis for nul(*A*) and describe nul(*A*) geometrically.
- (b) Give a basis for col(A) and describe col(A) geometrically.
- 2. Let $T : \mathbb{R}^2 \to \mathbb{R}^2$ be the linear transformation defined by $T(\vec{\mathbf{x}}) = A\vec{\mathbf{x}}$ where $A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$.
 - (a) Find a basis for ker(T) and describe ker(T) geometrically.
 - (b) Find a basis for range(T) and describe range(T) geometrically.
 - (c) Describe *T* in geometric terms.
 e.g. "*T* rotates the plane by ^π/₃ radians counter-clockwise", or "*T* projects the plane onto the *x*-axis", etc. To be clear, *T* doesn't do either of these, but these are examples of how you can describe *T*. It may be useful to pick a few specific points in ℝ² and see what their image is under *T*.
- 3. Show that $\mathcal{B} = \{4 31t 7t^2, 1 + t, 5t + t^2\}$ is not a basis for \mathbb{P}_2 .
- 4. (a) Let $S = {\vec{v_1}, \vec{v_2}, ..., \vec{v_k}}$ be a set of vectors in \mathbb{R}^n with k < n. Use a theorem from earlier in the semester to explain why *S* cannot be a basis for \mathbb{R}^n .
 - (b) Let $S = {\vec{v_1}, \vec{v_2}, ..., \vec{v_k}}$ be a set of vectors in \mathbb{R}^n with k > n. Use a theorem from earlier in the semester to explain why *S* cannot be a basis for \mathbb{R}^n .

(These problems are essentially the same as Exercises 4.3.29 and 4.3.30 from the text, Lay's Linear Algebra, 4th edition)

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